# Wedge Cam Operation Slide Guide

# MHK2 Series

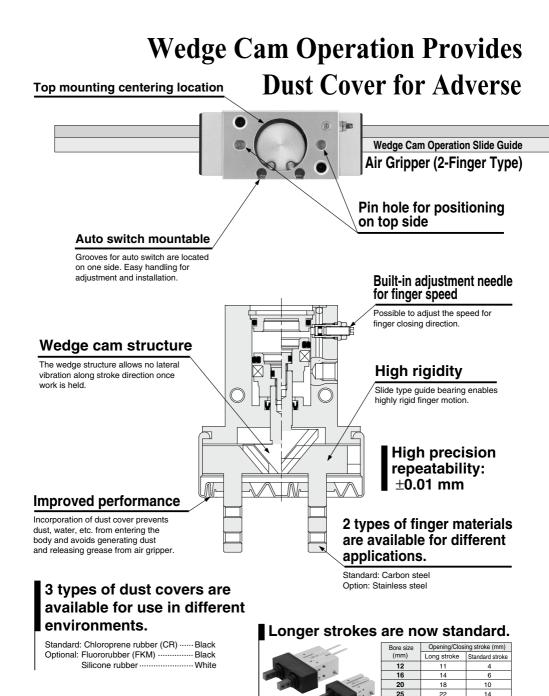
## Air Gripper/2-Finger Type Ø12, Ø16, Ø20, Ø25



#### Load Resistant, Dust Cover for Adverse Environments 2 types of finger materials 3 types of dust cover materials

Standard: Carbon steel Option: Stainless steel Standard: Chloroprene rubber (CR) ····· Black Optional: Fluororubber (FKM) ····· Black Silicone rubber ···· White

**SMC** 

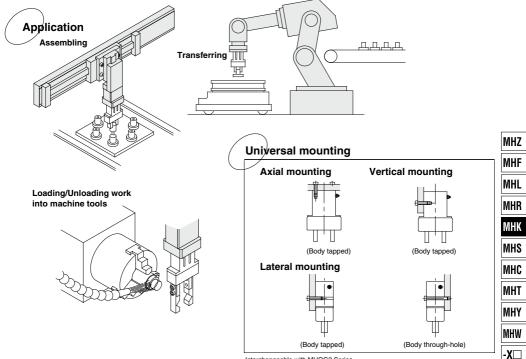


© SMC

# High Precision and Rigidity. Environmental Conditions.



# MHK2 Series



#### Interchangeable with MHQG2 Series

@SMC

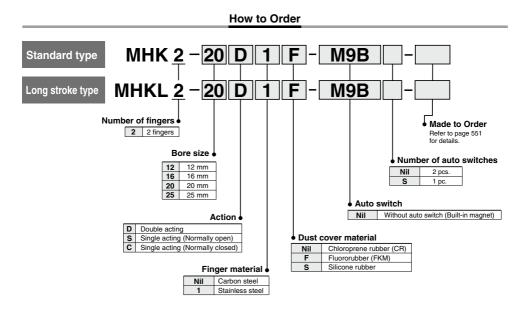
#### Series Variations

	Series	Model	Bore size (mm)	Opening/Closing stroke (mm)	Option
		MHK2-12□	12	4	Finger option Carbon steel (Standard),
ing	Standard type	MHK2-16□	16	6	Stainless steel
opening/closing	MHK2 Series	MHK2-20□	20	10	Dust cover option Chloroprene rubber (Standard)
ing/		MHK2-25□	25	14	Fluororubber
ben		MHKL2-12	12	11	Silicone rubber Auto switch
lelo	Long stroke type	MHKL2-16	16	14	Solid state switch
Parallel	MHKL2 Series	MHKL2-20	20	18	D-M9N(V), D-M9P(V) D-M9B(V), Water resistant
٩.		MHKL2-25	25	22	(2-color indicator), D-M9□A(V)



MRHQ

MA D-



Applicable Auto Switches/Refer to pages 797 to 850 for further information on auto switches.

	Special		la dia atau	Marine a		oad volta	200	Auto Swit	ch model	Lead wir	e len	gth	(m)*			
Туре			Indicator				age	Electrical en	ntry direction	0.5	1	3	5		Applica	ble load
	function	entry	light	(Output)	D	С	AC	Perpendicular	In-line	(Nil)	(M)	(L)	(Z)	CONNECTOR		
				3-wire (NPN)		5 V,		M9NV	M9N	•	•	٠	0	0	IC	
switch	_			3-wire (PNP)		12 V		M9PV	M9P	•	•	٠	0	0	circuit	
SWI				2-wire		12 V		M9BV	M9B	•	•	٠	0	0	_	
auto	Disersais			3-wire (NPN)		5 V,		M9NWV	M9NW	•	•	٠	0	0	IC	Relay.
	Diagnosis (2-color indicator)	Grommet	Yes	3-wire (PNP)	24 V	12 V	-	M9PWV	M9PW	•	•	٠	0	0	circuit	PLC
state				2-wire		12 V		M9BWV	M9BW	•	•	٠	0	0	_	
id.	Mater and sinte at			3-wire (NPN)		5 V,		M9NAV**	M9NA**	0	0	٠	0	0	IC	1
Solid	Water resistant (2-color indicator)			3-wire (PNP)		12 V		M9PAV**	M9PA**	0	0	٠	0	0	circuit	
	(2-0001 Indicator)			2-wire		12 V		M9BAV**	M9BA**	0	0	٠	0	0	_	

\*\* Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.

\* Lead wire length symbols: 0.5 m ······ Nil (Example) M9NW

- 1 m ······· M (Example) M9NWM 3 m ······ L (Example) M9NWL
- 5 m ······· Z (Example) M9NWZ

Note) When using the 2-color indicator type, please make the setting so that the indicator is lit in red to ensure the detection at the proper position of the air gripper.

\* Auto switches marked with a "O" symbol are produced upon receipt of order.

#### Specifications



#### Symbol



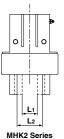
Single acting/

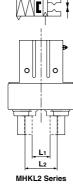
Double acting: External grip

Normally open: External grip

Single acting/ Normally closed: Internal grip







Made to Order

Made to Order: Individual Specifications (For details, refer to pages 565 and 566.)

Symbol	Specifications/Description
-X39	With grease nipple
-X41	Auto switch groove (Both-side type)

### Order

#### Made to Order Click here for details

Symbol	Specifications/Description
-X4	Heat resistance (100°C)
-X5	Fluororubber seal
-X7	Closing direction spring assist
-X12	Opening direction spring assist
-X50	Without magnet
-X53	EPDM seal/Fluorine grease
-X63	Fluorine grease
-X64	Finger: Side tapped mounting
-X65	Finger: Through-hole mounting
-X77A	Dust cover adhesion
-X77B	Dust cover adhesion (Finger part only)
-X78A	Dust cover caulking
-X78B	Dust cover caulking (Finger part only)
-X79	Grease for food processing machines, Fluorine grease
-X79A	Grease for food processing machines

Fluid			Air
<b>a</b>	Dou	ble acting	0.1 to 0.6 MPa
Operating	Single	Normally open	0.25 to 0.6 MPa
pressure	acting	Normally closed	
Ambient and	fluid temp	erature	-10 to 60°C
Repeatability	1		±0.01 mm
Lubrication			Not required
Action			Double acting/Single acting
Auto switch	Auto switch (Option) Note)		Solid state auto switch (3-wire, 2-wire)

Note) Refer to pages 797 to 850 for further information on auto switches.

#### Option

[	Finger material	Carbon steel (Standard), Stainless steel
	Dust cover material	Chloroprene rubber (CR) (Standard), Fluororubber (FKM), Silicone rubber

#### Model

#### MHK2 Series/Standard Type

		nes/otune		7					
Actio	n	Model	Bore size (mm)	Max. operating frequency (c.p.m)	Effective gripping force per finger (N)	Opening/Closing stroke (mm) L2-L1	Width at closing (mm) L1	Width at opening (mm) L2	Weight (g)
Double acting		MHK2-12D	12		External grip: 15 Internal grip : 16	4	9	13	75
		MHK2-16D	16		External grip: 31 Internal grip : 36	6	14.6	20.6	113
		MHK2-20D	20		External grip: 46 Internal grip : 56	10	16	26	235
Ď		MHK2-25D	25		External grip: 80 Internal grip : 86	14	19	33	440
	e	MHK2-12S	12	120	9	4	9	13	76
	y op	MHK2-16S	16		23	6	14.6	20.6	114
бu	Normally open	MHK2-20S	20		34	10	16	26	237
acting	2 Z	MHK2-25S	25		58	14	19	33	443
Single a	closed	MHK2-12C	12		12	4	9	13	76
si Si		MHK2-16C	16		25	6	14.6	20.6	115
	Normally	MHK2-20C	20		44	10	16	26	237
	Nori	MHK2-25C	25		73	14	19	33	443

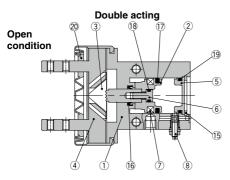
#### MHKL2 Series/Long Stroke Type

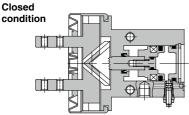
Actio	on	Model	Bore size (mm)	Max. operating frequency (c.p.m)	Note) Effective gripping force per finger (N)	Opening/Closing stroke (mm) L2-L1	stroke (mm) closing oper			
Double acting		MHKL2-12D	12		External grip: 14 Internal grip : 16	11	9	20	104	
		MHKL2-16D	16		External grip: 27 Internal grip : 30	14	14.6	28.6	164	
		MHKL2-20D	20		External grip: 45 Internal grip : 53	18	16	34	312	
ă		MHKL2-25D	25		External grip: 79 Internal grip : 90	22	19	41	562	
	en	MHKL2-12S	12	90	9	11	9	20	105	
	y op	MHKL2-16S	16		17	14	14.6	28.6	165	
ĝ	Normally open	MHKL2-20S	20		32	18	16	34	314	
acting	R	R	MHKL2-25S	25		53	22	19	41	565
Single	peg	MHKL2-12C	12		11	11	9	20	105	
Si	/ clos	MHKL2-16C	16		22	14	14.6	28.6	166	
	Normally closed	MHKL2-20C	20		40	18	16	34	314	
	Noi	MHKL2-25C	25		63	22	19	41	565	

Note) At the pressure of 0.5 MPa, when gripping point L is 20 mm. Single acting nomally open: External holding force, Single acting nomally closed: Internal gripping force. Refer to "Effective Gripping Force" for the gripping force at each gripping position on pages 553 to 557.



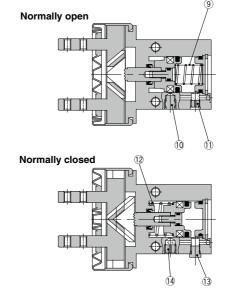
#### Construction





#### **Component Parts**

No.	Description	Material	Note
1	Body	Aluminum alloy	Hard anodized
2	Piston	Aluminum alloy	Hard anodized
3	Cam	Carbon steel	Heat treated, Specially treated
4	<b>Firmer</b>	Carbon steel	
4	Finger	Stainless steel 304	Option
5	Сар	Aluminum alloy	Hard anodized
6	Piston bolt	Stainless steel	
7	Rubber magnet	Synthetic rubber	



Single acting

No.	Description	Material	Note
8	Needle assembly		
9	N.O. spring	Piano wire	
10	Plug	Brass	Electroless nickel plated
11	Exhaust plug	Brass	Electroless nickel plated
12	N.C. spring	Piano wire	
13	Plug assembly	Brass	Electroless nickel plated
14	Exhaust plug A	Brass	Electroless nickel plated
15	Type C retaining ring	Carbon steel	Nickel plated

#### **MHK2 Replacement Parts**

Description			MHK2-12□	MHK2-16□	MHK2-20	MHK2-25□	Main parts	
Seal kit			MHK12-PS	MHK16-PS	MHK20-PS	MHK25-PS	16171819	
Piston asse	mb	ly	MHK-A1201	MHK-A1601	MHK-A2001	MHK-A2501	267	
Cam			P3318103	P3318203	P3318303	P3318403	3	
<b>Fireman</b>	Material	Carbon steel	P3318104	P3318204	P3318304	P3318404	(4)	
Finger	Mat	Stainless steel	P3318104-1	P3318204-1	P3318304-1	P3318404-1	4	
Needle ass	emb	ly		MHK-	A1206		8	
		CR	MHK2-J12	MHK2-J16	MHK2-J20	MHK2-J25		
Dust cover	ater	FKM	MHK2-J12F	MHK2-J16F	MHK2-J20F	MHK2-J25F	20	
	Σ	Silicone rubber	MHK2-J12S	MHK2-J16S	MHK2-J20S	MHK2-J25S		

\* Order 2 pieces per one finger unit. Replacement part/Grease pack part no.: MH-G01 (30 g)

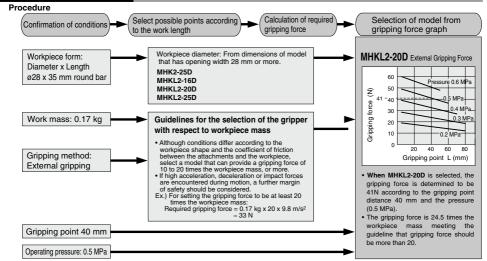
#### MHKL2 Replacement Parts

Description		n	MHKL2-12	MHKL2-16	MHKL2-20	MHKL2-25	Main parts
Seal kit		MHK12-PS	MHK16-PS	MHK20-PS	MHK25-PS	16171819	
Piston asse	mb	ly	MHK-A1201	MHK-A1601	MHK-A2001	MHK-A2501	267
Cam			P3318111	P3318211	P3318311	P3318411	3
Finner	Material	Carbon steel	P3318112	P3318212	P3318312	P3318412	(4)
Finger	Mat	Stainless steel	P3318112-1	P3318212-1	P3318312-1	P3318412-1	(4)
Needle asse	Needle assembly			MHK-A1206			8
	rial	CR	MHKL2-J12	MHKL2-J16	MHKL2-J20	MHKL2-J25	
Dust cover	Mater	FKM	MHKL2-J12F	MHKL2-J16F	MHKL2-J20F	MHKL2-J25F	20
	ž	Silicone rubber	MHKL2-J12S	MHKL2-J16S	MHKL2-J20S	MHKL2-J25S	

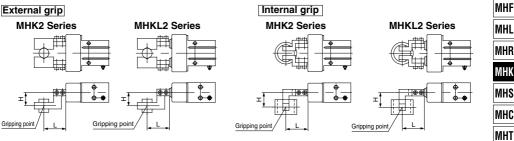
\* Order 2 pieces per one finger unit. Replacement part/Grease pack part no.: MH-G01 (30 g)



#### Model Selection Example



#### **Gripping Point**

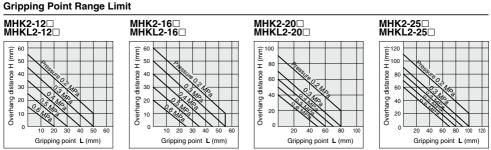


L: Gripping point distance

H: Overhang distance

- Proper gripping points should be selected in accordance with the operating pressure. The distance to the gripping point L and the overhang distance H should be within the limited range given in the graphs below.
- When the gripping point distance becomes large, the inger attachment applies an excessively large load to

the finger sliding section, causing excessive play of the fingers and possibly leading to premature failure.



Note) Distance to the gripping point L of single acting type is shortened by spring return. Use air gripper within gripping force line shown for each pressure in effective gripping force graph.



MHZ

MHY

MHW

-X□

MRHO

MA

D-

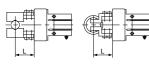
#### Effective Gripping Force: MHK2 Series Double Acting

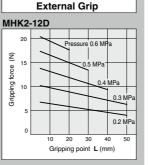
 Indication of effective gripping force The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.

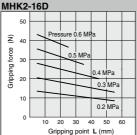


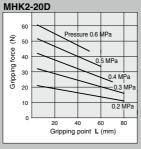


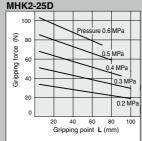
Internal grip MHK2 Series

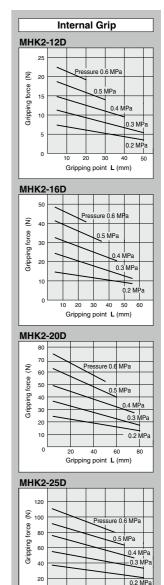












0

20

40 60 80 100

Gripping point L (mm)

#### Effective Gripping Force: MHKL2 Series Double Acting

 Indication of effective gripping force The effective gripping force shown in the **External Grip** Internal Grip graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and MHKL2-12D MHKL2-12D attachments are in full contact with the workpiece as shown in the figure below. 20 25 Pressure 0.6 MPa Pressure 0.6 MPa ŝ ŝ 20 15 Gripping force \_0.5 MPa Gripping force 0.5 MPa 15 0.4 MPa 10 0.4 MPa 10 0.3 MPa 0.3 MPa 5 5 0.2 MPa 0.2 MPa 0 0 10 20 30 40 50 10 20 30 40 50 Gripping point L (mm) Gripping point L (mm) External grip Internal grip MHKL2-16D MHKL2-16D MHKL2 Series MHKL2 Series 50 50 ŝ Ē 40 40 Pressure 0.6 MPa Gripping force Pressure 0.6 MPa Gripping force 30 30 0.5 MPa 0.5 MPa 0.4 MPa MPa 20 0.4 20 0.3 MPa 0.3 MPa 10 10 0.2 MPa 0.2 MPa 0 0 10 20 30 40 50 60 20 40 50 60 10 30 Gripping point L (mm) Gripping point L (mm) MHKL2-20D MHKL2-20D 80 60 70 Pressure 0.6 MPa ŝ ŝ 50 60 Pressure 0.6 MPa Gripping force Gripping force 0.5 MPa 50 40 MPa 40 30 0.4 MPa .4 MPa 30 0.3 MPa 20 0.3 MPa 0.2 MPa 20 10 10 0.2 MPa 0 0 20 40 60 80 20 40 60 80 Gripping point L (mm) Gripping point L (mm) MHKL2-25D MHKL2-25D 100 120 sure 0.6 MPa ŝ Î 100 80 Pressure 0.6 MP Gripping force Gripping force 0.5 MPa 80 60 0.5 MPa 0.4 MPa 60 0.4 MPa 40 0.3 MPa 40 0.2 MPa 0.3 MPa 20 20 0.2 MPa 0 0 20 40 60 80 100 20 40 60 80 100 Gripping point L (mm) Gripping point L (mm)

MHL MHR MHK MHK MHC MHT MHY MHW A MRHQ D-D-

MHZ

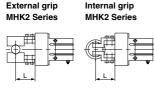
MHF

#### Effective Gripping Force: MHK2 Series Single Acting

 Indication of effective gripping force The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.



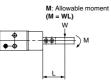
Note) In case of single acting type, the value is for stroke center.

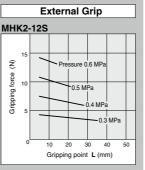


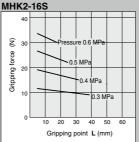
 Precautions when using the single acting type: If a moment such as that illustrated below is applied to the finger, the finger might not be able to retract by the spring force alone. Therefore, make sure to use the air gripper within the allowable moment that is indicated in the table below.

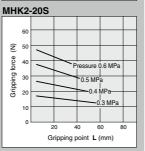
#### **Allowable Moment**

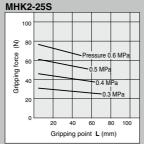
Model	Allowable moment (N·m)	
MHK2-12S/C	0.05	
MHK2-16S/C	0.12	
MHK2-20S/C	0.25	
MHK2-25S/C	0.49	

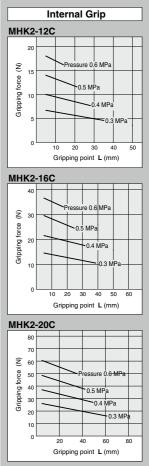




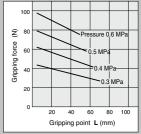








**MHK2-25C** 



#### Effective Gripping Force: MHKL2 Series Single Acting

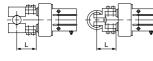
· Indication of effective gripping force The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.



Note) In case of single acting type, the value is for stroke center.

External grip MHKL2 Series



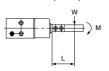


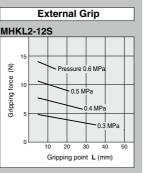
· Precautions when using the single acting type: If a moment such as that illustrated below is applied to the finger, the finger might not be able to retract by the spring force alone. Therefore, make sure to use the air gripper within the allowable moment that is indicated in the table below.

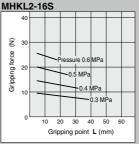
#### **Allowable Moment**

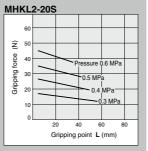
Model	Allowable moment (N·m)	
MHKL2-12S/C	0.05	
MHKL2-16S/C	0.12	
MHKL2-20S/C	0.25	
MHKL2-25S/C	0.49	

M: Allowable moment (M = WL)

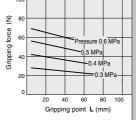


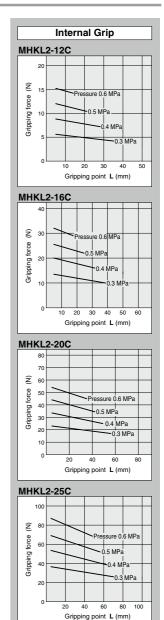


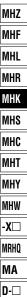






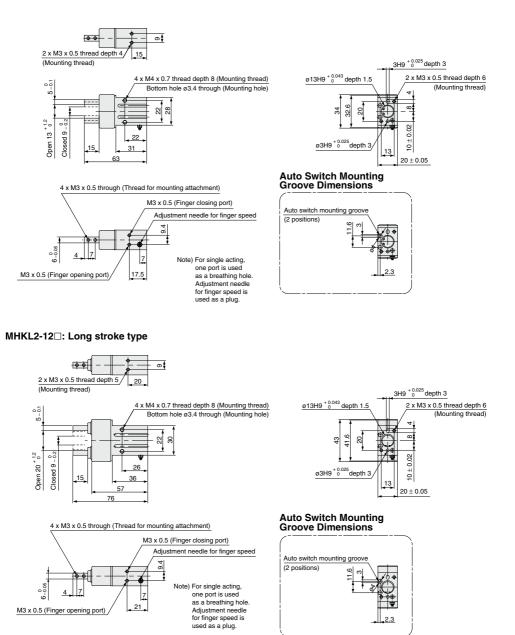




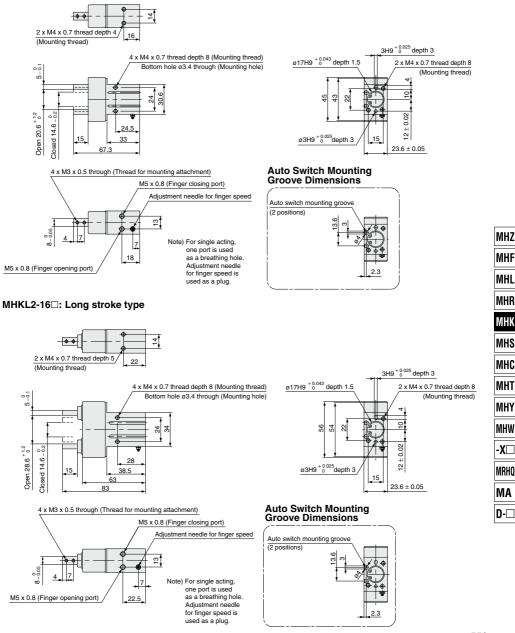


#### Dimensions

#### MHK2-12 : Standard type

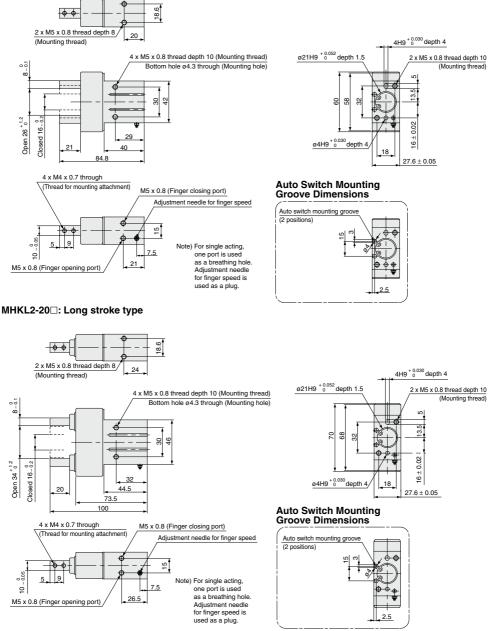


#### MHK2-16 : Standard type

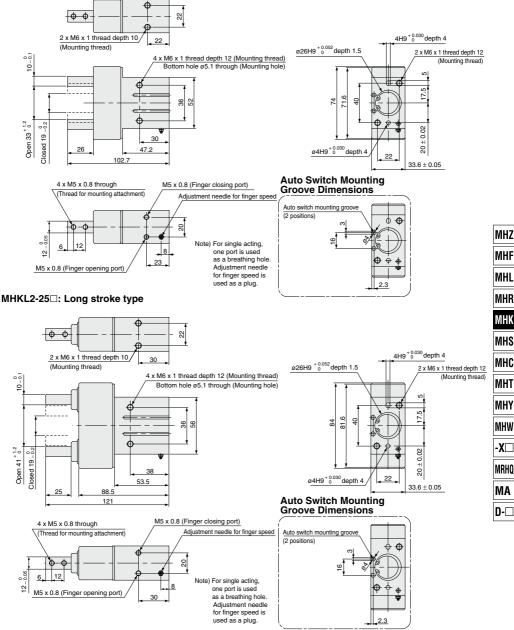


#### Dimensions

#### MHK2-20 : Standard type



#### MHK2-25 : Standard type



# MHK2/MHKL2 Series Auto Switch Installation Examples and Mounting Positions

Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions. 1) Detection when Gripping Exterior of Workpiece

I	Detection exa	ample	1. Confirmation of fingers in reset position	2. Confirmation of workpiece held	3. Confirmation of workpiece released		
Position to be detected			Position of fingers fully opened	Position when gripping a workpiece	Position of fingers fully the second		
Operation of auto switch			Auto switch turned ON when fingers return. (Light ON)	Auto switch turned ON when gripping a workpiece. (Light ON)	When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light ON)		
Detection combinations	One auto so * One position, a and ③ can be	ny of 1, 2	•	•	•		
n cor	Two auto switches	E A	•	•	_		
ectio	* Two positions of		_	•	•		
Det	<ol> <li>(1), (2) and (3) ca be detected.</li> </ol>	" <sup>©</sup> C	•	_	•		
iı	How to dete auto swit nstallation po	ch	Step 1) Fully open the fingers.	Step 1) Position fingers for gripping a workpiece.	Step 1) Fully close the fingers.		
	no pressure		Step 2) Insert the auto switch into the auto	switch installation groove in the direction sh	nown in the following drawing.		
	essure, conr to switch to a						
su	pply, and fol						
dir	ections.						
			Step 3) Slide the auto switch in the	Step 3) Slide the auto switch in the direc	tion of the arrow until the light illuminates		
			direction of the arrow until the indicator light illuminates.	position where the indicator light illuminates.			
				Position where light turns ON			
			<b>►</b> 1				
			Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out.				
				0.3 to 0	5 mm		
				0.0100	<u></u>		
			Step 5) Move the auto switch in the	Position to be secured			
			opposite direction and fasten it at a		€		
			position 0.3 to 0.5 mm beyond the position where the indicator light				
			illuminates.	<b>*</b> !			
			Position where light turns ON				
			0.3 to 0.5 mm				
			Position to be				
			▲				

Note 1) It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.

Note 2) When holding a workpiece close at the end of open/close stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.



Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions. 2) Detection when Gripping Interior of Workpiece

1	Detection exa	mple	1. Confirmation of fingers in reset position	2. Confirmation of workpiece held	3. Confirmation of workpiece released	
be detected fingers fully		fingers fully	Position when gripping a workpiece	Position of fingers fully opened		
	Operation of auto switch		Auto switch turned ON when fingers return. (Light ON)	Auto switch turned ON when gripping a workpiece. (Light ON)	When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light ON)	
Detection combinations	One auto sw * One position, and and ③ can be de	y of (1), (2) etected.	•	•	•	
tion c	Two auto switches	Pattern <b>B</b>	•	•		
Detec	* Two positions of ①, ② and ③ can be detected.		•		•	
	How to deter auto switc nstallation pos	mine h	Step 1) Fully close the fingers.	Step 1) Position fingers for gripping a workpiece.	Step 1) Fully open the fingers.	[
At	no pressure	or low	Stop 2) Incort the oute quitability the out	switch installation groove in the direction s	hown in the following drawing	MHZ
pre au	to switch to a pply, and follo	ect the power	Step 2) insert the auto switch into the auto		nown in the ronowing drawing.	MHF
	ections.	ow the				
			Step 3) Move the auto switch in the direction of the arrow and fasten it at a	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates.		MHR
			position 0.3 to 0.5 mm beyond the position where the indicator light illuminates.			МНК
						MHS
						MHC
			_ <b>-</b>	Step 4) Slide the auto switch further in the light goes out.	e direction of the arrow until the indicator	MHT
			0.3 to 0.5 mm			MHY
			── <u>{</u> ── <del>─</del> ─────────────────────────────────			MHW
			<b>→</b>	direction indicated by the arrow from its	opposite direction 0.3 to 0.5 mm in the location when the indicator light comes on	-XD
				again.		
				Position where light turns ON	3□€	
				│		<b>D</b> -□
				0.3 tr	o 0.5 mm	
				secured		
				_ <b>←</b>		

Note 1) It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.

Note 2) When holding a workpiece close at the end of open/close stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.



#### Auto Switch Hysteresis

Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.

Auto switch operating position (ON)

 Auto switch return position (OFF)

 Max. hysteresis (mm)

 D-M9⊡(V)

 D-M9⊡K(V)

 MHK□2-12
 0.1

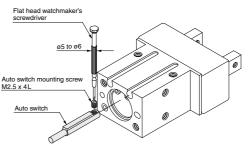
 MHK□2-20
 0.3

02

MHK□2-25

#### Auto Switch Mounting

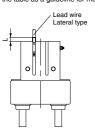
To set the auto switch, insert the auto switch into the installation groove of the gripper from the direction indicated in the following drawing. After setting the position, tighten the attached auto switch mounting set screw with a flat head watchmaker's screwdriver.

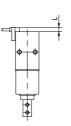


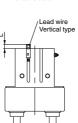
Note) Use a watchmaker's screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch mounting screw. Also, tighten with a torque of about 0.05 to 0.15 N-m, or about 0.05 to 0.10 N-m for D-M9CIA(V).

#### Protrusion of Auto Switch from Edge of Body

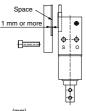
The amount of auto switch protrusion from the body's end surface is as shown in the table below.
Use the table as a guideline for mounting.







Note) When auto switch for MHK2, MHKL2 is set on mounting side as figure below, allow for at least 1 mm on mounting plate since the auto switch is protruded from edge of gripper.



					(mm)
	Lead wire type	In-line electri	cal entry type	Perpendicular electrial entry type	Perpendicular electrial entry type
Auto Finger position	o switch model	D-M9□ D-M9□W	D-M9□A	D-M9⊟V D-M9⊟WV	D-M9□AV
MHK2-12□	Open	_	—	-	—
MHK2-12	Closed	3	5	-	3
	Open	_	_	-	_
MHK2-16□	Closed	3	5	1	3
MHK2-20□	Open	_	_	-	_
MHK2-20	Closed	1	3	-	1
	Open	—	—	-	_
MHK2-25□	Closed	2	4	—	2
MHKL2-12	Open	_	_	-	_
MHKL2-12	Closed	3	5	-	3
	Open	—	—	-	_
MHKL2-16	Closed	3	5	1	3
	Open	_	_	_	_
MHKL2-20	Closed	1	3	-	1
	Open	_	_	-	_
MHKL2-25	Closed	1	3	-	1

Note) There is no protrusion if no values are entered in the table.



# MHK2 Series Made to Order: Individual Specifications 1

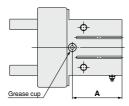


#### Symbol 1 With Grease Nipple -X39 Lubrication from grease cup to interior is possible. How to Order MHK X39 Standard part number With Grease Nipple Specifications Bore size (mm) 16, 20, 25 Note 1) Fill lubricant to the bearing from the grease Action Double acting, Single acting (Normally open, Normally closed) cup in order to prevent foreign particles from Lubricant grease MHK standard grease (MH-G01) getting in. The use of special grease MH-G01 for MHK is recommended. Refer to the dimensions and figure below Grease nipple position Note 2) Not compatible with ø12. Specifications/dimensions Same as the standard type

Dimensions (Dimensions other than specified below are the same as the standard type.)

#### MHK2 Series MHKL2 Series

other than the above



	(mm)
Model	Α
MHK2-16□□-X39	30.5
MHK2-20 -X39	37.5
MHK2-25 C-X39	45
MHKL2-16□□-X39	36
MHKL2-20	42
MHKL2-25	47.5

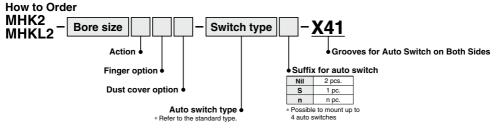
MHZ
MHF
MHL
MHR
MHK
MHS
MHC
MHT
MHY
MHW
<b>-X</b> □
MRHQ
MA
<b>D-</b> □

# *MHK2 Series* Made to Order: Individual Specifications 2

#### 2 Grooves for Auto Switch on Both Sides

Symbol

It is possible to select the auto switch mounting side. A maximum of 4 auto switches are mountable.

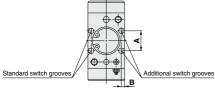


#### Specifications

Bore size (mm)	12, 16, 20, 25
Additional switch groove position	Refer to the dimensions and figures below.
Specifications/dimensions other than the above	Same as the standard type

Dimensions (Dimensions other than specified below are the same as the standard type.)

#### MHK2 Series MHKL2 Series



		(mm)
Model	Α	В
MHK2-12	10.4	1.8
MHK2-16	12.8	1.6

\* Dimensions A and B of other models are same as standard switch grooves.



### MHK2 Series **Specific Product Precautions**

Be sure to read this before handling the products.

#### Pssible to mount from 3 directions.

### Mounting Air Grippers/MHK2 Series

#### Axial Mounting (Body tapped)



Model	Applicable bolts		Max. screw-in depth L mm		
MHK2 -12□ MHKL2-12□	M3 x 0.5	0.88	6		
MHK2 -16□ MHKL2-16□	M4 x 0.7	2.1	8		
MHK2 -20□ MHKL2-20□	M5 x 0.8	4.3	10		
MHK2 -25 MHKL2-25	M6 x 1	7.3	12		

#### Vertical Mounting (Body tapped)



Model	Applicable bolts	Max. tightening torque N·m	Max. screw-in depth L mm
MHK2 -12	M3 x 0.5	0.59	4
MHKL2-12	M3 x 0.5	0.74	5
MHK2 -16	M4 x 0.7	0.88	4
MHKL2-16	M4 x 0.7	1.3	5
MHK2 -20□ MHKL2-20□	M5 x 0.8	3.3	8
MHK2 -25□ MHKL2-25□	M6 x 1	5.9	10

#### Lateral mounting (Body tapped and through-hole)

#### Body tapped



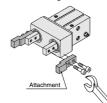
Model	Applicable bolts	Max. tightening torque N·m	Max. screw-in depth L mm
MHK2 -12□ MHKL2-12□	M4 x 0.7	2.1	8
MHK2 -16□ MHKL2-16□			8
MHK2 -20□ MHKL2-20□	M5 x 0.8	4.3	10
MHK2 -25□ MHKL2-25□	M6 x 1	7.3	12

#### Body through-hole

Model	Applicable bolts	Max. tightening torque N·m
MHK2 -12 MHKL2-12 MHK2 -16 MHK2 -16 MHKL2-16	M3 x 0.5	0.88
MHK2 -20□ MHKL2-20□	M4 x 0.7	2.1
MHK2 -25□ MHKL2-25□	M5 x 0.8	4.3

#### How to Mount the Attachment to the Finger

- To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
- · Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger



Model	Applicable bolts	Max. tightening torque N·m
MHK2 -12 MHKL2-12 MHK2 -16 MHKL2-16	M3 x 0.5	0.59
MHK2 -20□ MHKL2-20□	M4 x 0.7	1.4
MHK2 -25□ MHKL2-25□	M5 x 0.8	2.8

MHZ
MHF
MHL
MHR
МНК
MHS
MHC
MHT
MHY
MHW
-X□
MRHQ
MA
<b>D-</b> □