



Compliant with the TM Series OMRON Corporation collaborative robot and the TM Series TECHMAN ROBOT Inc. collaborative robot

Plug and Play

configuration for immediate use

TMComponent Easy programming





(E RoHS





More information can be viewed here



P-E20-24

Plug and

Vacuum Gripper Unit

for Collaborative Robots

OMRON Corporation and TECHMAN ROBOT Inc.

TM5, TM12, and TM14 compliant

Operate by simply connecting 1 air supply tube and an electrical wiring M8 connector.

- Integrated vacuum ejector, air supply/release valve, pressure sensor, and cups
- Standards: Conforming to ISO9409-1-50-4-M6
- TMComponent (Refer to page 5.)



end cups

Adsorption Unit Variations

The number of cups can be changed.







1 cup

2 cups

4 cups

The cup type can be changed. (For details on selectable cups, refer to "How to Order.")



Flat (ø8), Silicone rubber







Thin flat (ø16), NBR



Flat (ø32), Silicone rubber Flat (ø32), Urethane rubber





ø32, 2.5-stage, Silicone rubber







ø25, 5.5-stage, Silicone rubber With vacuum saving valve Silicone rubber



Vacuum saving valve ZP2V Series (To be ordered separately) Applicable part no.: ZP2V-B6-05

* The silicone material is compliant with the FDA (U.S. Food and Drug Administration) regulation 21CFR§177.



The cup with flange can be used separately (if using an external vacuum source).



*1 When using a cup with flange, be sure to order a One-touch fitting for vacuum pressure supply (part number: KQ2L08-01NS) and a vacuum port plug (part number: M-5P) separately.



How to Order





Applicable cups

* Refer to the Web Catalog for details on suction cups.

4	6	6	7	8	Cup with adapter					Adapter unit	
Cup	Cup	Cup	Cup	Attach-		Weight	by cup	material	(g/cup)	/ Vacuum inlet: \	Cup unit
series	diameter	form	material	ment	Part no.	N	S/SF	U	F	Male thread M6 x 1	p
70				mont		(NBR)	(Silicone)	(Urethane)	(FKM)	1 /	
	08	U U				4	4	4	4		
	80	<u> </u>				4	4	4	4	7074 40	
<u></u>	10					4	4	4	4	ZP11-A6	
	13					4	4	4	4		
_ <u>ZP</u>	16	01				4	4	4	4		
<u></u>	10	<u> </u>					1	/	/		
<u></u>	13	<u> </u>				1	1	/	8	ZP12-7A-X2	
<u></u>	16	<u> </u>				/	1	1	8		
<u></u>	20	U			ZPG200/A-X2	9	10	10	10	ZPT3-7A-X2	
ZP	25	U			ZPG25UU-7A-X2	10	10	10	11		ZP25U
ZP	32	<u> </u>			ZPG32UU-7A-X2	10	11	11	12		ZP32U
ZP	10	C			ZPG10C7A-X2	7	7	7	7	ZPT2-7A-X2	ZP10C
ZP	13	<u> </u>			ZPG13CU-7A-X2	7	7	7	7		ZP13C
ZP	16	<u>C</u>			ZPG16C -7A-X2	7	7	7	8		ZP16C
ZP	20	C			ZPG20CL-7A-X2	9	10	10	11		
ZP	25	C			ZPG25C7A-X2	10	10	10	11	ZPT3-7A-X2	ZP25C
ZP	32	С			ZPG32C□-7A-X2	10	11	11	12		ZP32C
ZP	10	В			ZPG10B	7	7	7	8		ZP10B
ZP	13	В			ZPG13BD-7A-X2	7	8	8	8	ZPT2-7A-X2	ZP13B
ZP	16	В			ZPG16BD-7A-X2	8	8	8	9		ZP16B
ZP	20	В			ZPG20B□-7A-X2	11	11	11	13		ZP20B
ZP	25	В			ZPG25B□-7A-X2	11	12	12	14	ZPT3-7A-X2	ZP25B
ZP	32	В			ZPG32B□-7A-X2	14	15	15	18		ZP32B
ZP	20	UT			ZPG20UTD-7A-X2	4	4	4	4	ZPT1-A6	ZP2-20UT
ZP	16	J			ZPG16J□-7A-X2	8	8	8	9	ZPT2-7A-X2	ZP2-16J
ZP	B25	J			ZPGB25J□-7A-X2	14	15	15	18	7072-74-82	ZP2-B25J
ZP	B30	J			ZPGB30J□-7A-X2	18	19	19	25	2F13-/A-A2	ZP2-B30J
ZP3P	20	JT2	SF		ZP3PG20JT2SF-7A-X2	—	21	—	—	ZP3PA-T1JT-7A-X2	ZP3P-20JT2SF-W
ZP3P	20	JT2	SF	М	ZP3PG20JT2SF-M-7A-X2	—	21	—			ZP3P-20JT2SF-WM
ZP3P	32	JT2	SF		ZP3PG32JT2SF-7A-X2	—	48	—	—	ZP3PA-T2JT-7A-X2	ZP3P-32JT2SF-W
ZP3P	32	JT2	SF	М	ZP3PG32JT2SF-M-7A-X2	—	48	—	—		ZP3P-32JT2SF-WM
ZP3P	20	JT5	SF		ZP3PG20JT5SF-7A-X2	—	23	—	—	ZP3PA-T1JT-7A-X2	ZP3P-20JT5SF-WG
ZP3P	25	JT5	SF		ZP3PG25JT5SF-7A-X2		25	—	_		ZP3P-25JT5SF-WG
ZP3P	32	JT5	SF		ZP3PG32JT5SF-7A-X2	_	54	_	_	ZP3PA-T2JT-7A-X2	ZP3P-32JT5SF-WG

Input the material symbol ("N," "S," "U," or "F") into the \Box in the part number.



Dimensions













* The dimensions and mounting method described in this drawing (example) are for the following part number: ZXP7A41-ZPB25JS-X1





More information on the TMComponent software can be viewed here.



Easy programming

Using the certified software TMComponent of OMRON Corporation and TECHMAN ROBOT Inc., various operations and sensor signals can be easily programmed by using a control box equipped with the dedicated software tool "TMflow" or by using graphical flowcharts on a Windows computer. You can easily install the software by inserting a USB with the TMComponent software package into a control box or Windows computer.

* Please download the TMComponent software package from the SMC website, and save it to a USB memory.









ZXP7 41-X1 Specific Product Precautions

Be sure to read this before handling the products. For safety instructions and vacuum equipment precautions, refer to the "Handling Precautions for SMC Products" and the "Operation Manual" on the SMC website: https://www.smcworld.com

Handling

ACaution

- 1. Strictly observe the precautions on vacuum equipment and safety when using the product. Additionally, select a cup size and material suitable to both the workpiece to be adsorbed and the atmosphere. Take safety measures so that any accident, such as the dropping of a workpiece, does not occur during adsorption transfer. For details, refer to the Web Catalog.
- 2. Use the product within the specification range. Use exceeding the compressed air pressure or voltage may result in serious damage due to reduced product performance.
- 3. Exhaust air is released from the opening in the product. Therefore, this exhaust air opening must not be blocked or restricted.

Mounting

▲ Caution

- 1. For details on the mounting method, refer to the Operation Manual.
- 2. Tighten to the specified tightening torque. If the tightening torque is exceeded, the body and the mounting screws may break. However, insufficient torque may cause displacement of the body and loosening of the mounting screws.
- 3. Do not drop, strike, or apply excessive impact to this product.

Doing so may result in damage to the internal parts of the body, solenoid valve, or pressure sensor. In some cases, this damage may result in a malfunction.

4. Hold the body when handling the product. Do not pull excessively on the M8 connector cable or pinch the cable when lifting the body. Failure to do so may result in damage to the solenoid valve or pressure sensor. In some cases, this damage may result in a failure or malfunction.

5. The bolts may loosen due to the operating conditions and environment. Be sure to conduct maintenance such as tightening the bolts periodically.

Wiring

ACaution

- 1. Avoid repeatedly bending or stretching the M8 connector cable as well as applying force to it.
- 2. Do not wire while energizing the product. Doing so may result in damage to the internal parts of the solenoid valve or pressure sensor. In some cases, this damage may result in a malfunction.
- 3. Do not disassemble the M8 connector cable or make any modifications, including additional machining. Doing so may cause human injury and/or an accident.

Piping

▲ Caution

1. Flushing of the inside of the pipes

Before piping is connected, it should be thoroughly blown out with air (flushing) or washed to remove chips, cutting oil, and other debris from inside the pipe.

2. Tube attachment

- Take a tube having no flaws on its periphery and cut it off at a right angle. When cutting the tube, use tube cutters TK-1, 2, 3, 5, or 6. Do not use pliers, nippers, scissors, etc. If cutting is done with tools other than tube cutters, the tube may be cut diagonally or become flattened, etc., making a secure installation impossible, and causing problems such as the tube pulling out after installation or air leakage. Allow some extra length in the tube.
- · Grasp the tube and push it in slowly, inserting it securely all the way into the fitting.

• After inserting the tube, pull on it lightly to confirm that it will not come out. If it is not installed securely all the way into the fitting, this can cause problems such as air leakage or the tube pulling out.

3. Tube detachment

• Push in the release button sufficiently, pushing its collar equally around the circumference.

- Pull out the tube while holding down the release button so that it does not come out. If the release button is not pressed down sufficiently, there will be increased bite on the tube and it will become more difficult to pull it out.
- When the removed tube is to be used again, cut off the portion which has been chewed before reusing it. If the chewed portion of the tube is used as is, this can cause trouble such as air leakage or difficulty in removing the tube.

4. Other Tube Brands

When using other than SMC brand tube, confirm that the following specifications are satisfied with respect to the tube outside diameter tolerance.

 Nylon tube 	within ±0.1 mm
 Soft nylon tube 	within ±0.1 mm

 \cdot Polyurethane tube within ±0.15 mm, within –0.2 mm

Do not use tube which do not meet these outside diameter tolerances. It may not be possible to connect them, or they may cause other trouble, such as air leakage or the tube pulling out after connection.

5. Piping

 Do not apply unnecessary forces, such as twisting, pulling, moment loads, vibration, impact, etc., on fittings or tubing.
 This will cause damage to fittings and will crush, burst, or release tubing.

Do not lift the product by the piping after the tube is connected.
 Doing so may result in damage to the One-touch tube fitting.
 For details, refer to the "Handling Precautions for SMC Products" on the SMC website: https://www.smcworld.com



Vacuum Gripper Unit

for Collaborative Robots



A Safety Instructions Be sure to read the "Handling Precautions for SMC Products" (M-E03-3) and "Operation Manual" before use.